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#### Active Suspension Conversion Kit For MST RMX 2.0

This is a suspension Conversion kit. To use SuperScale2k20 SS Unit, This kit can use the full potential of the SS unit instantly. And you can get the realistic motion for your MST RMX chassis.

All of the parts are made with Color Fabb HT automobile grade tough and durable material. \*without body mounts, etc.

### Future

- · Come with All of parts and electronic, without SS unit.
- Design for MST RMX2.0
- Active suspension and conventional suspension hybrid.
- Simple and reliable, easy to swap design
- Fully compatible original suspension geometry

## What is contained in this kit?

Parts list of this kit

	Name	note	quantity
1	FrontStruttower		1
2	FrontstrutArms		2
3	RearStrutower		1
4	RearStrutArm		2
5	FixScrew	M3*12	4
6	FrontServoBackle		1
7	Rear ServoBackle		1
	Screw etc kit		
8	servo FixScrew	M3*10	16
9	TaperWasher	orange Alu	4
10	Screw	M3*8	4
12	M3 Nut	M3	5
13	Ballend	Yokomo4.8	4
14	ballStud	Tamiya	1set
15	TurnBackle	Yokomo4.8	4
16	Rodend	4.8	8
17	HardSpring RED	Tamiya	1set
18	HardSprihg Gray	Tamiya	1set
			sum
	Accessory kit		
19	servo Hone	PETG	4
20	SSunitMount	CFHT	1
21	Body mount	TPU	2





#### What you need (items not included in kit)

- Superscale2K20 SS unit kit
- MST RMX2.0 Chassis kit
- Radio Control kit
- Battery,ESC,Motor, Servo for drift, Gyro for Driftsrtvo

### 1, Installation

Use M3 screw, M3 Nut and gently insert to the M3 Nut position.



Use the screw to pull the nut into M3 Nut position

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The M3 nut will be flush when it is installed correctly

# 2, High Torque Servo installs



Use M3\*10 CapScrew(PartsNo13) to screw servos to chassis mount brackets.

The mount screw hole size is 2.8mm and optimize the tolerance for M3 Screw. The Servo's output shaft should be <u>on the side closest to chassis mount holes</u>.





## 3, Remove the bumper



# 4, Swap the Strut tower bar(Front)

Front Strut (Remove the original Strut Tower)



Remove the ball end and fix it in a same position Referer to page 14



Use a Tamiya Fluorne coated Stabilizer Ball connector set For the front, use this one.(partsNo17)



Assemble the front Strut tower by adding M3\*15 screws for the front. Do not over tighten. Check



for minimum play and movement.

The assembled strut tower needs a little bit friction. If this part is too loose, the SS's multiplier value can't increase, and serious oscillation will occur and won't stop. However, regular suspension linkage parts have to always be very smooth.



Check Ball connector position.





## 5, Swap the Strut tower bar (Rear)

Rear Strut Remove the original Strut Tower



Assembling the Rear Strut tower: (Assembled) Using M3\*12 screw for the Rear. (Do not over tighten) Check minimum play (The arms should move easily.)

The assembled strut tower needs a little bit friction. If this part is too loose, the SS's multiplier value can't increase, and serious oscillation will occur and won't stop. However, regular suspension linkage parts have to always be very smooth.

Use a Tamiya Fluorne coated Stabilizer Ball connector set For the Rear, use this one.(partsNo17)







## 6, Mounting the servo holder

Frontside



Side screw use 3\*15 Countersunk screw.(partsNo10) center screw. Use the screw that MST original used.

The \*Front servo holder has 3 screws. The rear servo holder has 2 screws.

#### **Rear Side**



Remove the original bumper and replace to Servo holder. About the Rear screw. Use the screw that MST original used.

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## 7, Initial setup of SS unit



Be aware of the gyro sensor position in SS unit

Firmware needed from SuperScale2k20

SUPERSCALE\_V1.2.ino.hex

\*this firmware is pre installed

### 8, How to setup SS unit

You need to install Arduino configuration software. Please download from the link below. <u>https://www.arduino.cc/en/Main/Software</u>

You may download Arduino IDE software for your suitable platform. MacOS or Win



### Step 1

First connect the SS unit to the PC and set the offset to 0. Next set BALANCE to 50. The servo 's neutral PWM value is almost 1500 FLpos 1500 RLpos 1500

\*you should provide the power for SS Unit cause USB doesn't provide enough power to move the servo neutral position.

### Step2

Check all of 4 servo is neutral position, and then <u>Set the servo horn like this</u>.



Servohorn and endball fix with M3x8 cap screw



This hone has tapered servo shaft connection, so any spline servo can perfect fit for this servo horn. so this servo horn material is PETG.

Use with Tapered washer like the photo, it is contain the kit (Parts No23).

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Servohorn cut image

### Step3

Adjust The turnbuckle length, and then connect servo and Strut arm.



Parts No16



Front and Rear Rod Length

### Front Rod length



#### Front=34mm

### RearRodLength



Rear=37mm

All about physical setup is done, please test the sample setting value.



#### MST sample setup value

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Carriage retu 🗸 115200 baud	<ul> <li>✓ Clear</li> </ul>	output

This is the start value to set up the active suspension More detail, please refer to SS unit manual.



Front Suspension Setting



Change the Front Spring to Red(partsNo19).



Rear Suspension Setting



Change the Front Spring to Gray (partsNo20).

It will be better to change more high viscosity dumper oil.



Body mount kit





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